The Variational Deficiency Bottleneck

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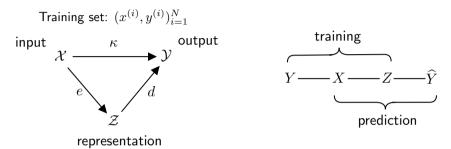
Joint work with Guido Montúfar (UCLA and MPI MiS)

International Joint Conference on Neural Networks WCCI 2020, Glasgow





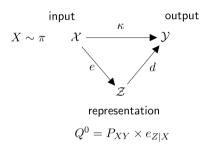
Learning representations for classification

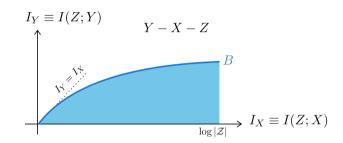


- X is an input variable (e.g., image) and Y an output variable of interest (e.g., label)
- The channel κ is unknown and only accessible through a training set
- Problem: Find a pair of stochastic maps (e,d) so that Z preserves as much relevant information as possible about the output (*sufficiency*) while maximally "compressing" the input (*minimality*)

The Information Bottleneck (IB)

$$(X,Y) \sim \pi \times \kappa$$





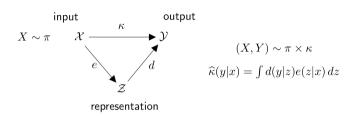
• Approximate minimal sufficiency: The IB maximizes

$$I_{Q^0}(Z;Y) - \beta I_{Q^0}(Z;X), \ \beta \in [0,1]$$

• IB curve: B is the (point-wise) smallest function for which

$$I(Z;Y) \leq B(I(Z;X)) \leq I(Z;X)$$
 for all $Y - X - Z$

The Deficiency Bottleneck (DB)



• The deficiency of d w.r.t. κ is

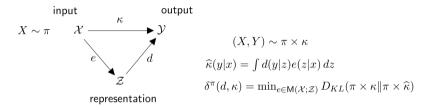
$$\delta^{\pi}(d,\kappa) := \min_{e \in \mathsf{M}(\mathcal{X};\mathcal{Z})} D_{KL}(\pi \times \kappa || \pi \times \widehat{\kappa})$$

The DB minimizes

$$\delta^{\pi}(d,\kappa) + \beta I(X;Z)$$

over all pairs (e,d), where $\beta \in [0,1]$ is a regularization parameter

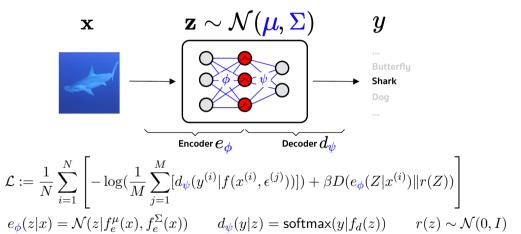
Deficiency and Input Blackwell Sufficiency



Definition (Input Blackwell sufficiency [Bla53, Nas18])

Given two channels, $\kappa \in \mathsf{M}(\mathcal{X}; \mathcal{Y})$ and $d \in \mathsf{M}(\mathcal{Z}; \mathcal{Y})$, κ is input-degraded from d, denoted $d \succeq_{\mathcal{Y}} \kappa$, if $\kappa = \int d(y|z)e(z|x)\,dz$ for some $e \in \mathsf{M}(\mathcal{X}; \mathcal{Z})$. We say that d is input Blackwell sufficient for κ if $d \succeq_{\mathcal{Y}} \kappa$.

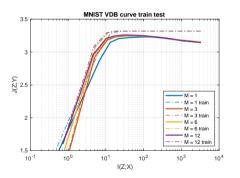
The Variational Deficiency Bottleneck (VDB)

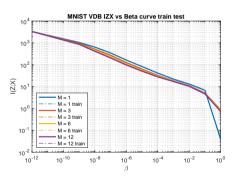


For M=1, we recover the Variational Information Bottleneck (VIB) objective [AFDM17]

The VDB curve for MNIST

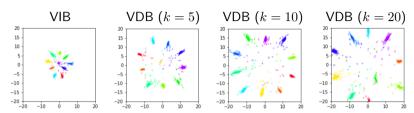
- In the VDB, "more sufficient" means "less deficient" $J(Z;Y) := H(Y) \mathbb{E}_{(x,y) \sim p_{\mathcal{D}}(x)} \left[-\log \widehat{\kappa}(y|x) \right]$
- Use M encoder samples to compute the expectation inside the log. J(Z;Y)=I(Z;Y) for M=1





• For good values of β , higher values of M (our method) lead to a *smaller generalization gap* and more compression of the input for the same level of sufficiency

2D representations for MNIST



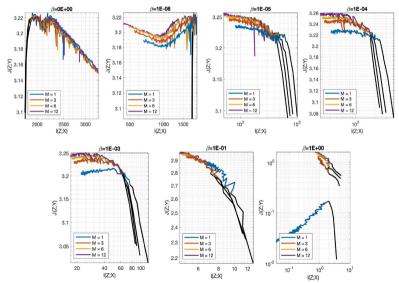
Posterior Gaussian distributions of 1000 test images from MNIST after training with the **VIB**, and the **VDB** with k=5,10,20 encoder update steps per decoder update. $\beta=10^{-3}$, M=1. Colors correspond to the 10 different class labels.

Nested optimization strategy to approximate the deficiency

$$\min_{d \in \mathsf{M}(\mathcal{Z};\mathcal{Y})} \left[\min_{e \in \mathsf{M}(\mathcal{X};\mathcal{Z})} \left[D(\pi \times \kappa \| \pi \times \widehat{\kappa}) + \beta D(\pi \times e \| \pi \times r) \right] \right], \quad \widehat{\kappa}(y|x) = \int d(y|z)e(z|x) \, dz$$

• Improved out-of-distribution robustness on MNIST-C [MG19] and CIFAR-10-C [HD19]

Information plane learning curves for MNIST



Conclusions

- A new bottleneck method for learning data representations based on information deficiency, rather than the more traditional information sufficiency
- VDB and VIB coincide in the regime of single-shot Monte Carlo approximations
- Training with the VDB improves out-of-distribution robustness over the VIB on two benchmark datasets, MNIST-C [MG19] and CIFAR-10-C [HD19]
- Unsupervised version of the VDB shares superficial similarities with the Importance Weighted Autoencoder (IWAE) [BGS16]





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